TATIANA KALGANOVA

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WORK EXPERIENCE

[10/2020 – Current] Director of Research Centre for AI: Social and Digital Innovation, Brunel University London London, UK

[11/2016 – Current] Member of the Advisory Academic Council of Institute of New Engineering and Materials Ural Federal University Yekaterinburg, Russia

[11/2016 – Current] Full Member of EPSRC Peer Review Associate College, EPSRC Peer Review Associate College UK

[08/2000 – Current] Senior Lecturer in Intelligent Systems Electronic and Computer Engineering School of Engineering and Design, Brunel University, London, UK

[2003 – 2011] Business Fellow, London Technology Network, London, UK

[1994 – 1997]Research Assistant Belarusian State University of Informatics and Radio-electronics, Minsk, Belarus

EDUCATION

[2008] PGCert in Learning and Teaching in Higher Education, Brunel University London , <u>www.bucks.ac.uk</u> London, UK

[1997 – 2000] PhD in Evolvable Hardware Napier University, <u>www.napier.ac.uk</u> Edinburgh, UK

[1997] Research-engineer Certificate- The program includes a set of modules on Pedagogy, Specialization,
Languages and Research methodology
Belarusian State University of Informatics and Radio-electronics, <u>www.bsuir.by</u>

Minsk, Belarus

[1989 – 1994] Masters in Control of Complex Systems Belarusian State University of Informatics and Radio-electronics, <u>www.bsuir.by</u> Minsk, Belarus

PUBLICATIONS /last 5 years/

[2022] "The Current State of the Art in Deep Learning for Image Classification: A Review", co-author, pp1-19, Lecture Notes in Networks and Systems, London, UK

[2021] "Dynamic impact for ant colony optimization algorithm", co-author, Swarm and Evolutionary Computation, 100993

[2021] "No routing needed between capsules" Neurocomputing, co-author, Volume 463, Pages 545-553, ISSN 0925-2312, <u>https://doi.org/10.1016/j.neucom.2021.08.064</u>

[2021] "Homogeneous Vector Capsules Enable Adaptive Gradient Descent in Convolutional Neural Networks" in IEEE Access 9, co-author, 48519-48530

[2021] A control structure for ambidextrous robot arm based on Multiple Adaptive Neuro-Fuzzy Inference System in John Wiley & Sons Ltd on behalf of The Institution of Engineering and Technology

[2020] "Accelerating supply chains with Ant Colony Optimization across a range of hardware solutions in Computers & industrial engineering 147, co-author, 106610